

ILS RWY 34R (CAT II & III)  
DENVER INTL (DEN)

**MISSED APPROACH:** Climb to 5800 then climbing left turn to 10000 on heading 270° and on FQF VORTAC R-306 to HYGEN/FQF 37.9 DME/RADAR and hold.

ROUTING TO BFREE  
(not to scale)

BFREE

10000 018° (2.7)

(IAF) TELLR 11000 210K

BHAPY

10000 353° (3.8)

10500 060° (2.2)

(IAF) LDORA 13000 210K

12000 064° (3.1)

FLUFF

BREKK

11000 018° (3.4)

11000 322° (3.1)

PAAAS

12000 279° (3.3)

(IAF) BOSSS 12000 210K

10000 24.6

OUF

RADAR 10000

The diagram illustrates a multi-robot system architecture. At the center is a Tower (TWR) connected to a network switch. Multiple robots, labeled A5 through A10, are positioned around the TWR. The environment includes various obstacles and dimensions, such as 16000 X 2000, 2000 X 150, 12000 X 150, and 12000 X 150. The robots are connected to the TWR via a network switch, and their positions are indicated by circles with labels.

REQUIRED

(IAF)  
BOSSS  
1000 210K

2000  
279°  
7.3

LOCALIZER 111.1  
I-OUF  
Chan 48

MSA DEN 25 NM  
9200

IM  
5478

CORDE  
I-OUF 7.1  
RADAR

DENVER  
117.9 DEN  
Chan 126

FALCON  
116.3 FQF  
Chan 110

7000  
(6.9)

BOENG  
I-OUF 14  
RADAR

9000  
(4.7)

BENGL  
I-OUF 18.7  
RADAR

(IF)  
BOOBU  
I-OUF 22  
RADAR

10000  
(3.2)

BFREE  
I-OUF 24.6  
RADAR  
10000

SEE INSET  
FOR ROUTING  
TO BFREE

ALTERNATE  
MISSED APCH FIX

114.2 GLL  
R-221  
Chan 89

HYGEN  
DEN 31.5  
RADAR

117.9 DEN  
Chan 126

22°  
302°  
R-302

6569

<p>VGSI and ILS glidepath not coincident (VGSI Angle 3.00/TCH 63).</p> <p>BFREE I-OUF 24.6 RADAR</p> <p>BOOBU I-OUF 22 RADAR</p> <p>BENGL I-OUF 18.7 RADAR</p> <p>BOENG I-OUF 14 RADAR</p> <p>CORDE I-OUF 7.1 RADAR</p> <p>5800 10000 hdg 270°</p> <p>FQF R-306</p> <p>HYGEN △</p>									
CATEGORY	A B C D								
S-ILS 34R	CAT II RA 155/12 100 DA 5454								
S-ILS 34R	CAT IIIa RVR 07								
S-ILS 34R	CAT IIIb RVR 03								
S-ILS 34R	CAT IIIc NA								

CATEGORY II & III ILS - SPECIAL AIRCREW  
& AIRCRAFT CERTIFICATION REQUIRED